

NuSMV

Hands-on introduction

F. Mallet

fmallet@unice.fr

Université Nice Sophia Antipolis

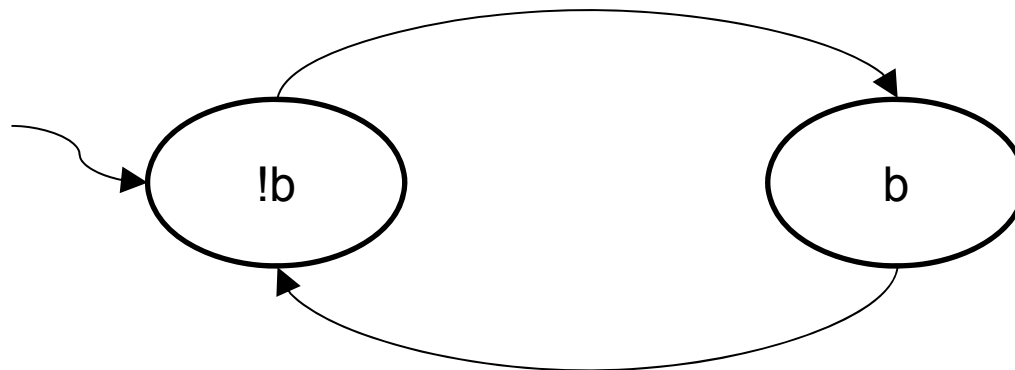
NuSMV 2

- NuSMV 1 was an extension of SMV
 - SMV : first BDD-based symbolic model-checker [McMillan, 90]

- NuSMV 2
 - Combines BDD-based and SAT-based model-checking
 - OpenSource licensing (GNU LGPL)

Kripke Structure

- Non-deterministic automaton used in model-checking (graph)
 - **[Nodes]** Finite reachable states of the system (S)
 - Set of initial states $I \subseteq S$
 - **[Edges]** state transition $R \subseteq S \times S$
 - Labeling function L
 - Maps each node to a set of properties that hold in the state



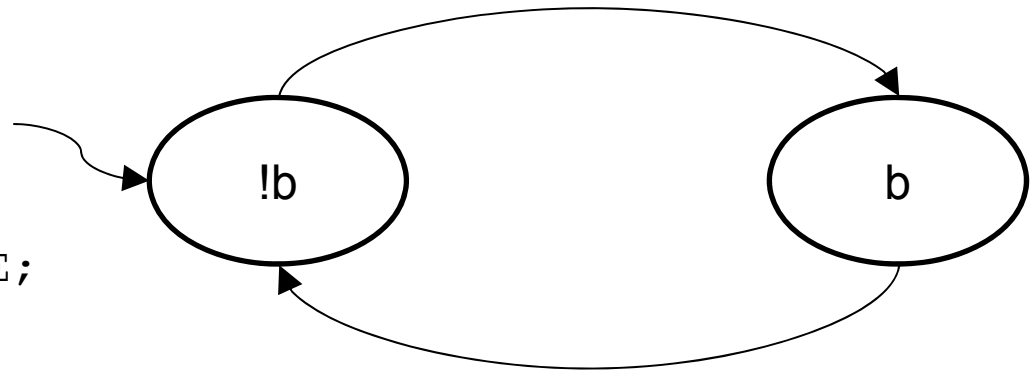
First NuSMV program

□ (Parameterized) Modules

- Declarations of state variables
 - The state variables determine the state space
 - The domain must be bounded (and small)
- Assignments
 - Valid initial states : `init`
 - Transition relation : `next`

□ Example

```
MODULE main
VAR b : boolean;
ASSIGN
  init(b) := FALSE;
  next(b) := !b;
```



Data types (1/2)

□ Boolean

- VAR

b : boolean;

FALSE, TRUE

□ Integer

- VAR

i : integer;

Signed 32-bit

j : 1..8;

□ Enumeration types

- VAR

thread : { stopped, running, waiting, finished }; Symbolic constants

t1 : { 2, 4, -2, 0 }; Integer enum

t2 : { FAIL, 1, 3, 7, OK }; Integer-and-symbolic

Data types (2/2)

□ Unsigned words (vectors of bits/boolean)

- VAR

b : unsigned word [3];

Unsigned 3-bit

□ Signed words (vectors of bits/boolean)

- VAR

i : signed word [7];

Signed 7-bit

□ Array

- VAR

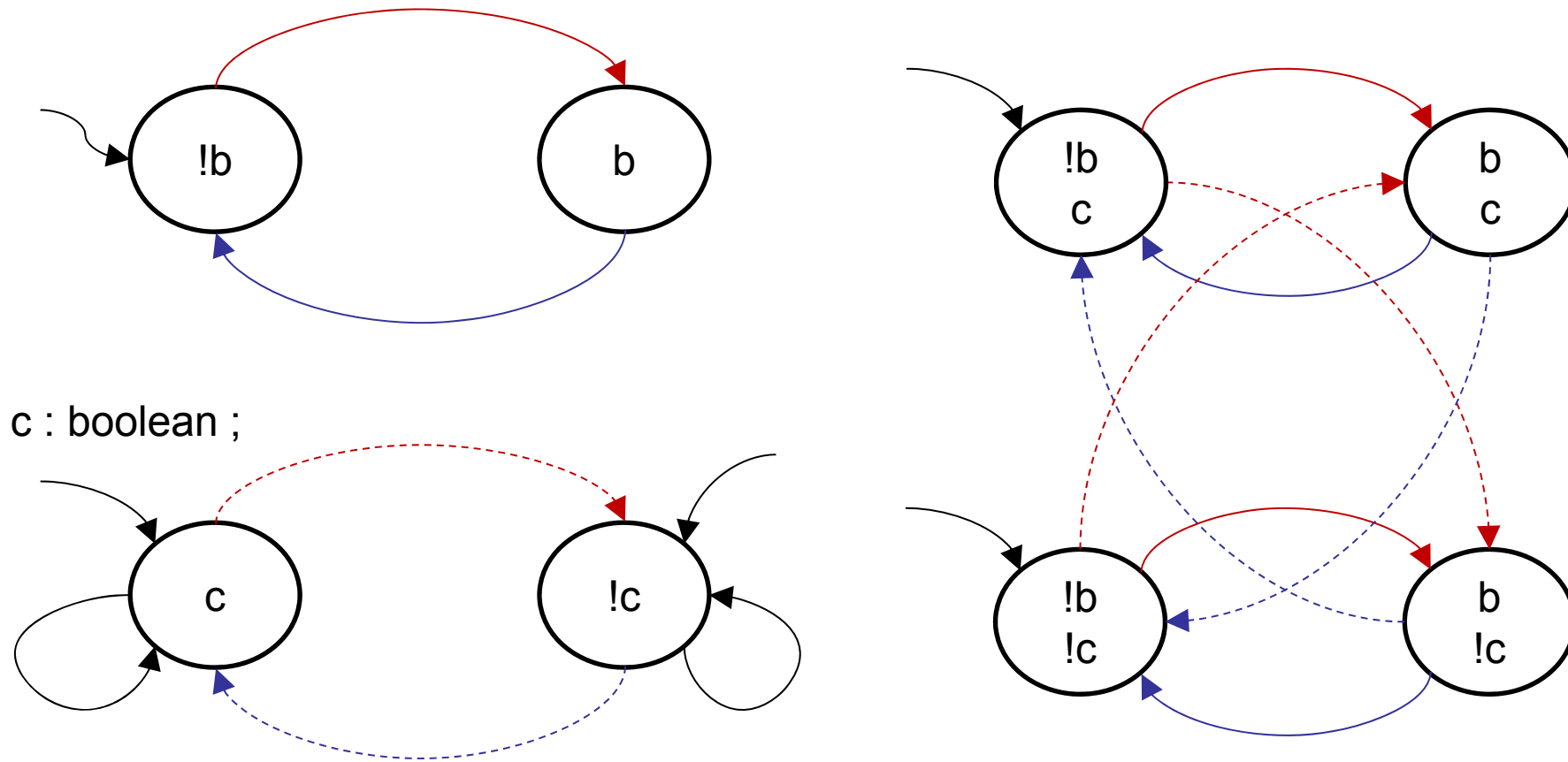
a : array 0..3 of boolean;

a1 : array 10..20 of {OK, y, z};

a2 : array 1..8 of array -1..2 of unsigned word[5];

Synchronous composition

- All the transitions evolve synchronously



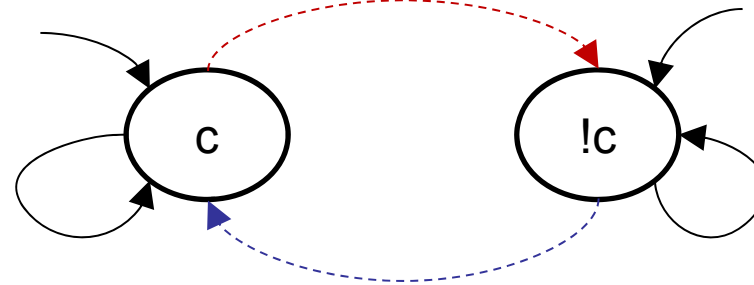
F. Mallet

Composed state-space=
Cartesian product

Initial states: **init**

□ If an initial value is not specified

- The variable can initially assume any value in its domain
 - `var c : boolean;`



□ Otherwise, an expression can compute (a set of) values in the definition domain

- `init(b) := FALSE ;` \Leftrightarrow `init(b) := { FALSE } ;`
- `init(c) := { TRUE, FALSE } ;` (non-deterministic)
- `init(var) := {a,b,c} union {x,y,z} ;`

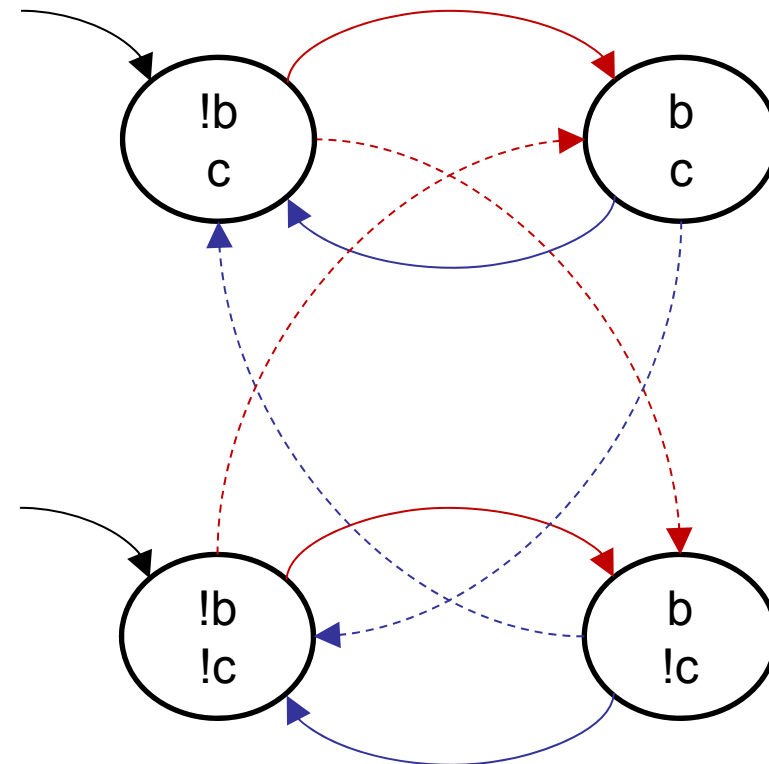
Initial states: **init**

□ Non-deterministic initialization

MODULE main**VAR**

b : boolean;

c : boolean;

ASSIGN**init**(b) := FALSE;**next**(b) := !b;Composed state-space=
Cartesian product

Initial states: **init**

□ Deterministic initialization

```
MODULE main
```

```
VAR
```

```
  b : boolean;
```

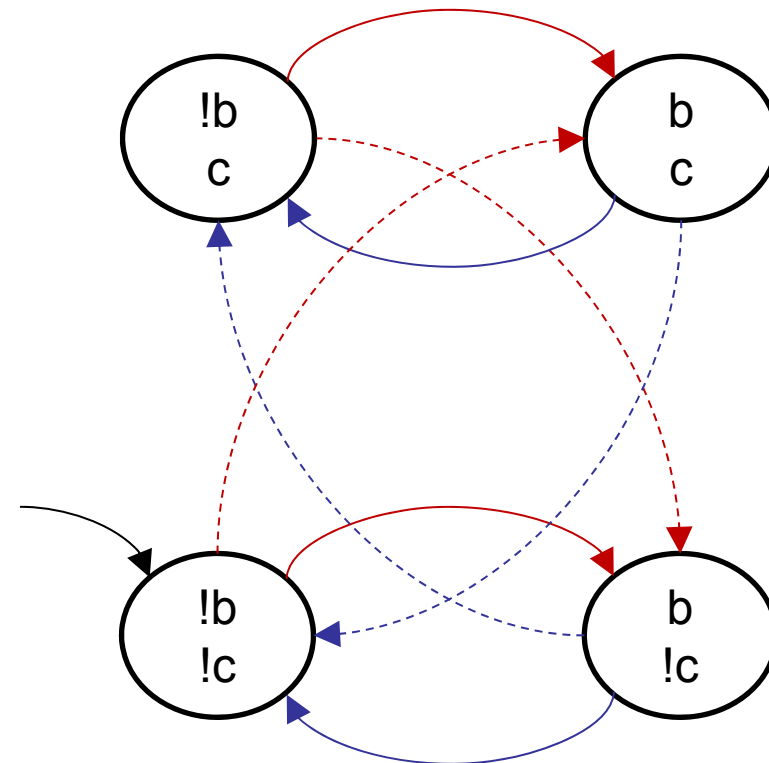
```
  c : boolean;
```

```
ASSIGN
```

```
  init(b) := FALSE;
```

```
  next(b) := !b;
```

```
  init(c) := FALSE;
```



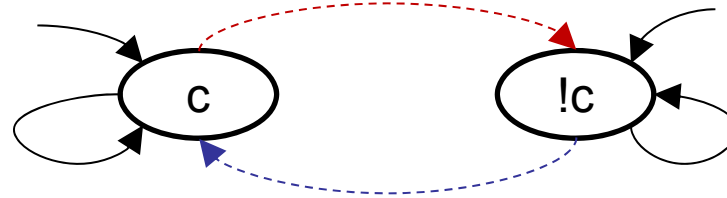
Composed state-space=
Cartesian product

Transition relation: **next**

- Constrain the values that a variable can assume in the next state
 - $\text{next}(\langle \text{variable} \rangle) := \langle \text{expression} \rangle;$
- $\langle \text{expression} \rangle$ depends on the definition domain of $\langle \text{variable} \rangle$
 - The expression can depends on current and next values of variables.
 - $\text{next}(\text{output}) := ! \text{input};$
 - $\text{next}(\text{output}) := (!\text{input}) \mathbf{union} \text{output};$
 - $\text{next}(b) := b + (\text{next}(a) - a);$

Transition relation: **next**

- If no next assignment
 - The variable evolves non-deterministically



Transition relation: **next**

□ Non-deterministic transition

MODULE main

VAR

b : boolean;

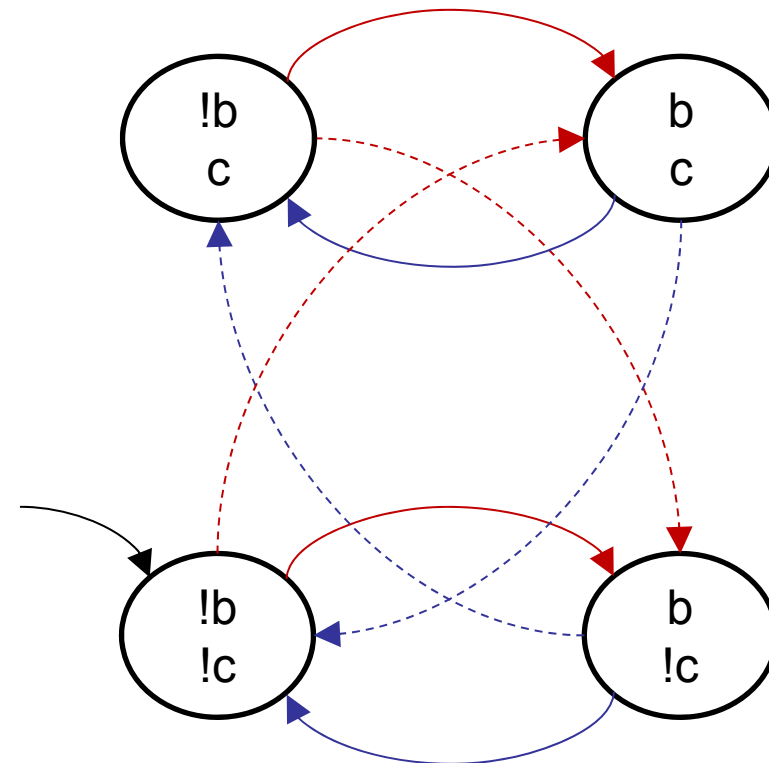
c : boolean;

ASSIGN

init (b) := FALSE;

next (b) := !b;

init (c) := FALSE;



Composed state-space=
Cartesian product

Transition relation: **next**

□ Deterministic transition

MODULE main

VAR

b : boolean;

c : boolean;

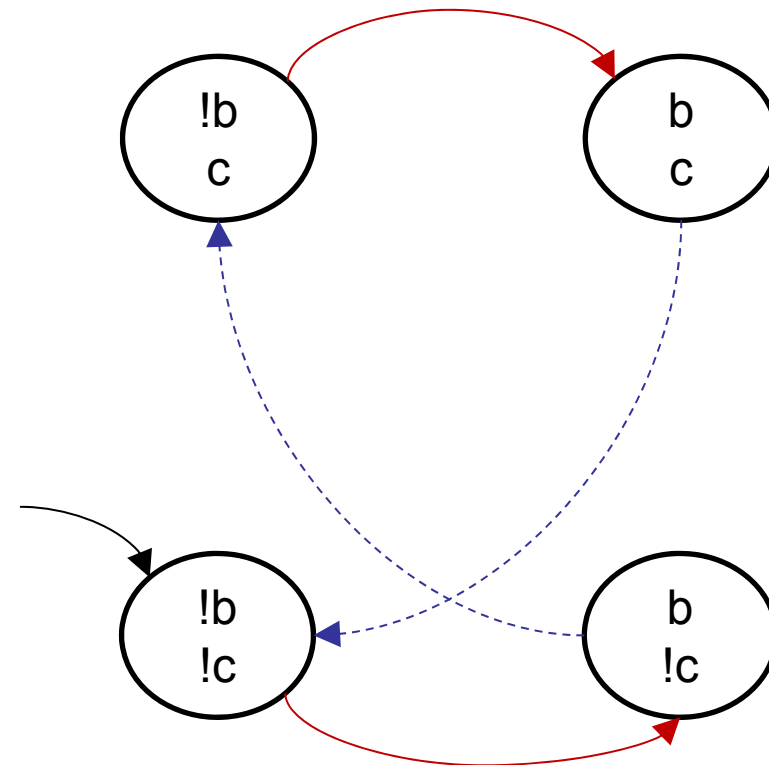
ASSIGN

init (b) := FALSE;

next (b) := !b;

init (c) := FALSE;

next (c) := (!b & c) |
(b & !c) ;



Composed state-space=
Cartesian product

Normal assignments

- When neither init nor next is used
 - Specify the current value of a variable depending on the current values of (other) variables
 - `<variable> := <expression> ;`

Normal assignments

□ Counter

```
MODULE main
```

```
VAR
```

```
  b : boolean;
```

```
  c : boolean;
```

```
  out : 0..3;
```

```
ASSIGN
```

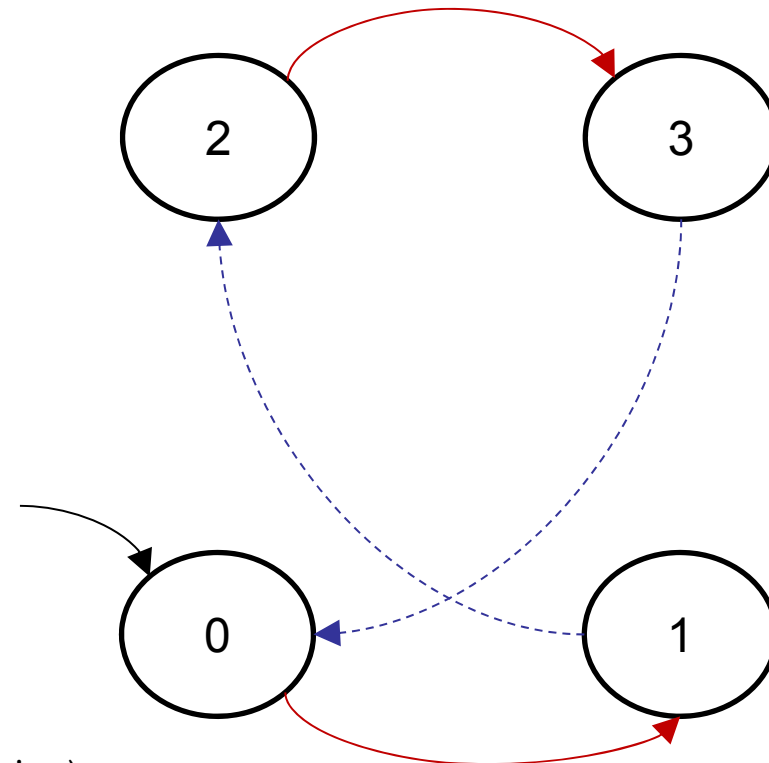
```
  init (b) := FALSE;
```

```
  next (b) := !b;
```

```
  init (c) := FALSE;
```

```
  next (c) := (!b & c) | (b & !c) ;
```

```
  out := b + 2*c;
```



Definitions

□ Counter

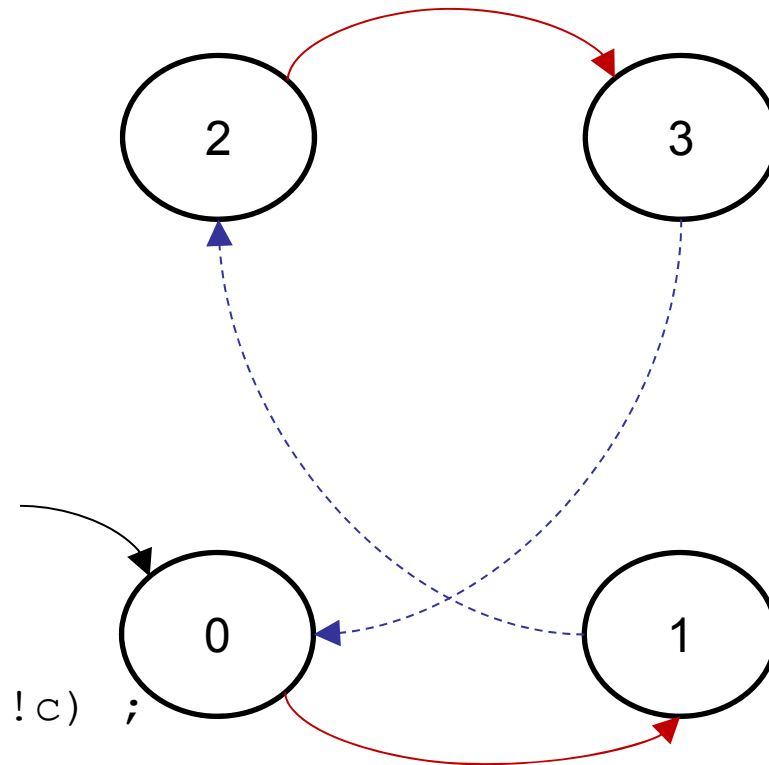
MODULE main**VAR**

b : boolean;

c : boolean;

ASSIGN**init** (b) := FALSE;**next** (b) := !b;**init** (c) := FALSE;**next** (c) := (!b & c) | (b & !c) ;**DEFINE**

out := b + 2*c;



Restrictions

□ Double-assignment rule

- Each variable may be assigned only once in the program
- **Example of illegal assignments**
 - `init(status) := ready;`
 - `status := busy;`

□ Circular-dependency rule

- A variable cannot have cycles in its dependency graph not broken by delays
 - `x := (x+1) ;` `next(x) := x & next(y);`
 - `next(y) := y & next(x);`

Simple example

□ Case expressions

- Keep the first condition that is evaluated to TRUE
- At least one condition must be TRUE

MODULE main

VAR

```
req : boolean;
state : {ready, busy};
```

ASSIGN

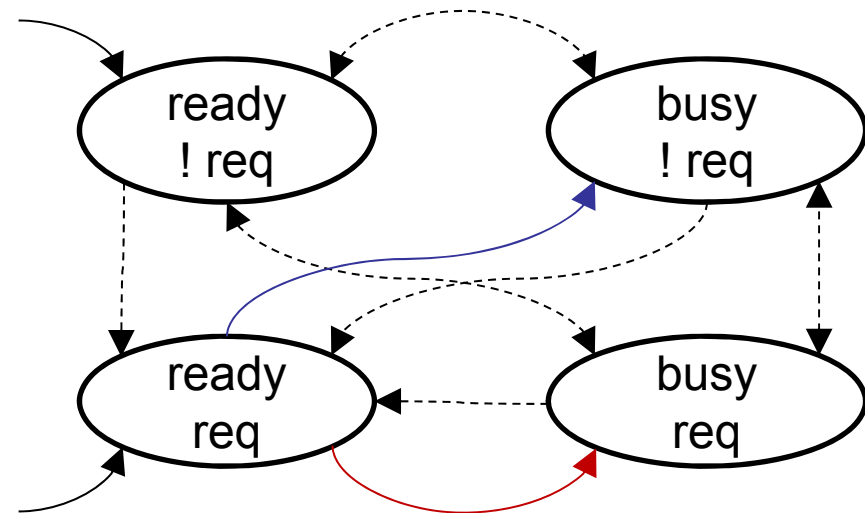
```
init(state) := ready;
```

```
next(state) := case
```

```
state = ready & req : busy;
```

```
TRUE : {ready, busy};
```

```
esac;
```



Module with parameters

□ 1-bit counter

```
MODULE count(carry_in)
```

```
VAR
```

```
  value : boolean;
```

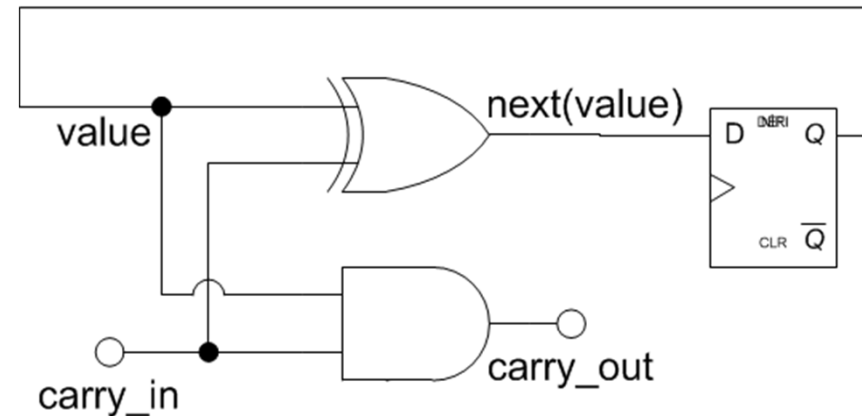
```
ASSIGN
```

```
  init(value) := FALSE;
```

```
  next(value) := value xor carry_in;
```

```
DEFINE
```

```
  carry_out := value & carry_in
```



Module with parameters

□ 3-bit counter

```
MODULE main
```

```
VAR
```

```
  bit0 : count(TRUE);
  bit1 : count(bit0.carry_out);
  bit2 : count(bit1.carry_out);
```

```
MODULE count(carry_in)
```

```
VAR
```

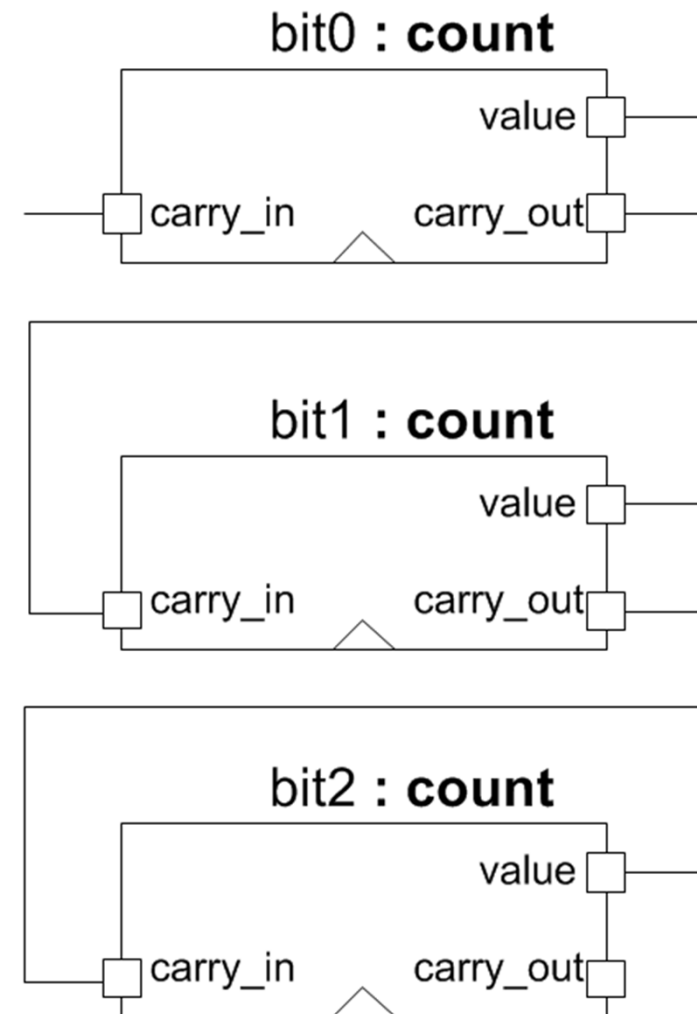
```
  value : boolean;
```

```
ASSIGN
```

```
  init(value) := FALSE;
  next(value) := value xor carry_in;
```

```
DEFINE
```

```
  carry_out := value & carry_in
```



Specifications

- Specifications are associated with modules
 - Each property is verified separately
 - Several kinds of specifications

- **Invariants**: `INVARSPEC`
 - Something that must always be true
 - A proposition on reachable states

- **Linear-Time Logics** (LTL) : `LTLSPEC`

- **Branching-Time Logics** (CTL) : `SPEC`

CTL formulas: **SPEC** (1/2)

```

ctl_expr ::
  simple_expr
| ( ctl_expr )
| ! ctl_expr
| ctl_expr & ctl_expr
| ctl_expr | ctl_expr
| ctl_expr xor ctl_expr
| ctl_expr xnor ctl_expr
| ctl_expr -> ctl_expr
| ctl_expr <-> ctl_expr

```

A CTL expression can be

- a simple expression (no next)
- Logical not
- Logical and
- Logical or
- Logical exclusive or
- Logical NOT exclusive or
- Logical implies
- Logical equivalence

CTL formulas: **SPEC** (2/2)

EG ctl_expr	<input type="checkbox"/> Exists globally
EX ctl_expr	<input type="checkbox"/> Exists next state
EF ctl_expr	<input type="checkbox"/> Exists finally
AG ctl_expr	<input type="checkbox"/> Forall globally
AX ctl_expr	<input type="checkbox"/> Forall next state
AF ctl_expr	<input type="checkbox"/> Forall finally
E [ctl_expr U ctl_expr]	<input type="checkbox"/> Exists until
A [ctl_expr U ctl_expr]	<input type="checkbox"/> Forall until

Invariants: **INVARSPEC**

□ Equivalent to

- SPEC AG simple_expr;

□ But

- Checked separately
- Can contain next operators

LTL formulas: **LTLSPEC** (1/3)

```

ltl_expr ::
  simple_expr
| ( ctl_expr )
| ! ctl_expr
| ctl_expr & ctl_expr
| ctl_expr | ctl_expr
| ctl_expr xor ctl_expr
| ctl_expr xnor ctl_expr
| ctl_expr -> ctl_expr
| ctl_expr <-> ctl_expr

```

A LTL expression can be

- a simple expression (no next)
- Logical not
- Logical and
- Logical or
- Logical exclusive or
- Logical NOT exclusive or
- Logical implies
- Logical equivalence

LTL formulas: **LTLSPEC** (2/3)

| **G** ltl_expr
 | **X** ltl_expr
 | **F** ltl_expr
 | p **U** q

| p **V** q

Future expressions

- globally
- next state
- finally
- Until
 - q must hold at some point (eventually)
 - p must hold all the time until then
 - p and q need not hold at the same time
- Releases
 - p must hold at all time $t' \geq t$ up to and including the time step t' where q also holds
 - q may never hold

LTL formulas: **LTLSPEC** (3/3)

| **H** ltl_expr
 | **Y** ltl_expr
 | **O** ltl_expr
 | p **S** q

| p **T** q

Past expressions

- historically
- previous state
- once
- Since
 - q must have held at some point ($t' \leq t$)
 - p must hold all the time at t' ($t' < t'' \leq t$)
 - p need not hold at t'
- Triggered
 - p held at $t' \leq t$
 - q holds at all t'' , ($t' \leq t'' \leq t$)
 - Or
 - p never held
 - q must hold at all t'' ($t_0 \leq t'' \leq t$)